

## Chapter 4

# The KdV problem in domains that can be transformed into rectangles

In this chapter, we study the Korteweg-de Vries equation subject to boundary condition in non-rectangular domain, with some assumptions on the boundary of the domain and the coefficients of equation. The right-hand side and its derivative with respect to  $t$  are in the Lebesgue space  $L^2$ . The goal is to establish the existence, the uniqueness and the regularity of the solution.

## 4.1 Introduction

Let  $\Omega \subset \mathbb{R}^2$  be the domain

$$\begin{aligned}\Omega &= \{(t, x) \in \mathbb{R}^2 : 0 < t < T, x \in I_t\}, \\ I_t &= \{x \in \mathbb{R} : \varphi_1(t) < x < \varphi_2(t), t \in (0, T)\},\end{aligned}$$

we consider the semi-linear Korteweg-de Vries problem with time variables coefficients

$$\begin{cases} \partial_t v(t, y) + a(t)v(t, y)\partial_y v(t, y) + b(t)\partial_y^3 v(t, y) = g(t, y) & \text{in } \Omega, \\ v(0, y) = 0, \quad y \in I_0, \\ v(t, \varphi_1(t)) = v(t, \varphi_2(t)) = \partial_y v(t, \varphi_2(t)) = 0 & t \in (0, T), \end{cases} \quad (4.1)$$

where  $I_0 = ]\varphi_1(0), \varphi_2(0)[$  and  $a(t)$ ,  $b(t)$  are given.  $g$  and  $\partial_t g$  are in  $L^2(\Omega)$ .

We are particularly interested in the question: What conditions on the functions  $a(t)$ ,  $b(t)$  and  $(\varphi_i(t))_{i=1,2}$  guarantee that (4.1) admits a unique solution  $u$ .

Consider the case where  $a(t)$ ,  $b(t)$ ,  $a'(t)$  and  $b'(t)$  are positive and bounded functions for all  $t \in [0, T]$ . Let  $h$  be defined by

$$\begin{aligned}h : [0, T] &\rightarrow [0, T'] \\ t &\mapsto h(t) = \int_0^t b(s) ds,\end{aligned}$$

we put  $\psi_i = \varphi_i \circ h^{-1}$  where  $i = 1, 2$ . Using the change of variables  $t' = h(t)$ ,  $w(t', y) = v(t, y)$ , (4.1) can be written in the form

$$\begin{cases} \partial_{t'} w(t', y) + d(t')w(t', y)\partial_y w(t', y) + \partial_y^3 w(t', y) = h(t', y) & (t', y) \in \Omega', \\ w(0, y) = 0, \\ w(t', \psi_1(t')) = w(t', \psi_2(t')) = \partial_y w(t', \psi_2(t')) = 0 & t' \in (0, T'), \end{cases}$$

where  $d(t') = \frac{a(t)}{b(t)}$ ,  $h(t', y) = \frac{g(t, y)}{b(t)}$ ,  $\Omega' = \{(t', x) \in \mathbb{R}^2; 0 < t' < T', x \in I_{t'}\}$  and

$$T' = \int_0^T b(s) ds.$$

So, to solve (4.1), it is enough to solve the following problem

$$\begin{cases} \partial_t v(t, y) + c(t)v(t, y)\partial_y v(t, y) + \partial_y^3 v(t, y) = g(t, y) & (t, y) \in \Omega, \\ v(0, y) = 0 & y \in I_0, \\ v(t, \varphi_1(t)) = v(t, \varphi_2(t)) = \partial_y v(t, \varphi_2(t)) = 0 & t \in (0, T). \end{cases} \quad (4.2)$$

In the sequel, we assume that there exist positive constants  $c_1$  and  $c_2$ , such that

$$\begin{aligned} c_1 &\leq c(t) \leq c_2, & \text{for all } t \in [0, T]. \\ c_1 &\leq c'(t) \leq c_2, & \text{for all } t \in [0, T]. \end{aligned} \quad (4.3)$$

We also impose the hypothesis

$$\varphi_1', \varphi_2', \varphi_1'', \varphi_2'', \varphi_1''', \varphi_2''' \in L^1(0, T) \quad (4.4)$$

to establish the existence and uniqueness of a solution to (4.1).

Then, for all  $t \in [0, T]$ , we have

$$|\varphi_1(t)| \leq |\varphi_1(0)| + \int_0^t |\varphi_1'(s)| \, ds \leq |\varphi_1(0)| + \int_0^T |\varphi_1'(s)| \, ds \leq \gamma,$$

where  $\gamma$  is a positive constant. Similarly, we have

$$\begin{aligned} |\varphi_2(t)| \leq \gamma, \quad |\varphi_1'(t)| \leq \gamma, \quad |\varphi_2'(t)| \leq \gamma, \\ |\varphi_1''(t)| \leq \gamma, \quad |\varphi_2''(t)| \leq \gamma, \end{aligned} \quad \text{for all } t \in [0, T] \quad (4.5)$$

therefore

$$|\varphi(t)| \leq 2\gamma, \quad |\varphi'(t)| \leq 2\gamma, \quad |\varphi''(t)| \leq 2\gamma \quad \text{for all } t \in [0, T], \quad (4.6)$$

where  $\varphi(t) = \varphi_2(t) - \varphi_1(t)$ .

The change of variables:

$$\begin{aligned} \Omega &\rightarrow R \\ (t, y) &\mapsto (t, x) = \left( t, \frac{y - \varphi_1(t)}{\varphi_2(t) - \varphi_1(t)} \right), \end{aligned} \quad (4.7)$$

transforms  $\Omega$  into the rectangle  $R = (0, T) \times I$  where  $I = (0, 1)$ . Putting  $v(t, y) = u(t, x)$  and  $g(t, y) = f(t, x)$ , Problem (4.2) becomes

$$\left\{ \begin{array}{l} \partial_t u(t, x) + \frac{c(t)}{\varphi(t)} u(t, x) \partial_x u(t, x) + \frac{1}{\varphi^3(t)} \partial_x^3 u(t, x) - \frac{x\varphi'(t) + \varphi_1'(t)}{\varphi(t)} \partial_x u(t, x) \\ = f(t, x) \quad (t, x) \in R, \\ u(0, x) = 0 \quad x \in I, \\ u(t, 0) = u(t, 1) = \partial_x u(t, 1) = 0 \quad t \in (0, T), \end{array} \right.$$

multiplying both sides of the equation of the last problem by  $\varphi^3(t) > 0$ , we obtain

$$\left\{ \begin{array}{l} p(t) \partial_t u(t, x) + q(t) u(t, x) \partial_x u(t, x) + \partial_x^3 u(t, x) + r(t, x) \partial_x u(t, x) \\ = f(t, x) \quad (t, x) \in R, \\ u(0, x) = 0 \quad x \in I, \\ u(t, 0) = u(t, 1) = \partial_x u(t, 1) = 0 \quad t \in (0, T), \end{array} \right. \quad (4.8)$$

where

$$p(t) = \varphi^3(t), \quad q(t) = \varphi^2(t)c(t) \quad \text{and} \quad r(t, x) = -\varphi^2(t)(x\varphi'(t) + \varphi_1'(t)).$$

It is easy to see that by change of variables (4.7) we have

$$\begin{aligned} g \in L^2(\Omega) &\Leftrightarrow f \in L^2(R) \\ v \in L^\infty(0, T, L^2(I_0)) &\Leftrightarrow u \in L^\infty(0, T, L^2(I)) \\ v \in L^2(0, T, H^3(I_0)) &\Leftrightarrow u \in L^2(0, T, H^3(I)) \end{aligned} \quad (4.9)$$

**Remark 4.1.** According to (4.3), (4.5) and (4.6), the functions  $p$ ,  $q$  and  $r$  satisfy the following assumptions

$$\left\{ \begin{array}{l} \alpha < p(t) < \beta, \quad \alpha < p'(t) < \beta \quad \forall t \in [0, T], \\ \alpha < q(t) < \beta, \quad \alpha < q'(t) < \beta \quad \forall t \in [0, T], \\ |r(t, x)| \leq \beta, \quad |\partial_x r(t, x)| \leq \beta, \quad \text{and} \quad |\partial_t r(t, x)| \leq \beta \quad \forall (t, x) \in R \end{array} \right. \quad (4.10)$$

where  $\alpha$  and  $\beta$  are positive constants.

Our main result is :

**Theorem 4.2.** *If  $f, \partial_t f$  are in  $L^2(\mathbb{R})$ , and  $p, q, r$  satisfy assumption (4.10), Problem (4.8) admits a unique solution such that*

$$\begin{aligned} u &\in L^\infty(0, T, L^2(I)) \cap L^2(0, T, H^3(I)), \\ \partial_t u &\in L^\infty(0, T, L^2(I)) \cap L^2(0, T, H^1(I)). \end{aligned}$$

**Corollary 4.3.** *If  $g, \partial_t g + \nu(t, y)\partial_y g$  are in  $L^2(\Omega)$ , and  $c(t), \varphi_1(t), \varphi_2(t)$  satisfy assumptions (4.3) and (4.4), Problem (4.1) admits a unique solution such that*

$$\begin{aligned} v &\in L^\infty(0, T, L^2(I_0)) \cap L^2(0, T, H^3(I_0)), \\ \partial_t v &\in L^\infty(0, T, L^2(I_0)) \cap L^2(0, T, H^1(I_0)). \end{aligned}$$

where  $\nu(t, y) = \frac{\varphi'(t)y - \varphi_1\varphi_2' + \varphi_1'\varphi_2}{\varphi(t)}$ .

We will prove Theorem 4.2, and thanks to the change of variables (4.7) and (4.9) the Corollary 4.3 will be a direct result of Theorem 4.2.

## 4.2 Preliminaries

**Lemma 4.4.** *There exist eigenfunctions of the following problem*

$$\begin{cases} e_j^{(4)} = \lambda_j e_j, & j \in \mathbb{N}^*, \\ e_j(0) = e_j(1) = e_j''(0) = e_j'(1) = 0. \end{cases}$$

which create a basis in  $H^4(I)$  orthonormal in  $L^2(I)$

*Proof.* For every  $f \in L^2(I)$  there exists a unique solution satisfying

$$\begin{cases} \partial_x^4 u = f, \\ u(0) = u(1) = u''(0) = u'(1) = 0. \end{cases} \quad (4.11)$$

Denote by  $T$  the operator  $f \mapsto u$  considered as an operator from  $L^2(I)$  into  $L^2(I)$ .

We claim that  $T$  is self-adjoint and compact. First, the compactness. Because of (4.11) we have

$$\int_0^1 (\partial_x^2 u)^2 dx = \int_0^1 f u dx$$

and thus

$$\begin{aligned}\|\partial_x^2 u\|_{L^2(I)}^2 &\leq \|f\|_{L^2(I)}^2 \|u\|_{L^2(I)}^2 \\ &\leq C \|f\|_{L^2(I)}^2\end{aligned}$$

where  $C$  is a positive constant. This can be written as

$$\|Tf\|_{H^2(I)}^2 \leq C \|f\|_{L^2(I)}^2, \quad \forall f \in L^2(I).$$

Since the injection of  $H^1(I)$  into  $L^2(I)$  is compact (because  $I$  is bounded), we deduce that  $T$  is a compact operator from  $L^2(I)$  into  $L^2(I)$ . Next, we show that  $T$  is self-adjoint, i.e.,

$$\int_0^1 (Tf)g \, dx = \int_0^1 f(Tg) \, dx, \quad \forall f, g \in L^2(I).$$

Indeed, setting  $u = Tf$  and  $v = Tg$ , we have

$$-\partial_x^4 u = f \tag{4.12}$$

and

$$-\partial_x^4 v = g \tag{4.13}$$

Multiplying (4.12) by  $v$  and (4.13) by  $u$  and then integrating, we obtain

$$\int_0^1 \partial_x^2 u \partial_x^2 v \, dx = \int_0^1 f v \, dx = \int_0^1 g u \, dx.$$

which is the desired conclusion.

Finally, we note that

$$\int_0^1 (Tf)f \, dx = \int_0^1 u f \, dx = \int_0^1 (\partial_x^2 u)^2 \, dx \geq 0, \quad \forall f \in L^2(I).$$

Hence, assertions of Lemma 4.4 follow from Theorem 6.1 [10].  $\square$

### 4.3 Parabolic regularization

To prove Theorem 4.2 , we consider in  $R = (0, T) \times (0, 1)$  the approximated problem

$$\begin{cases} p(t)\partial_t u_\varepsilon(t, x) + q(t)u_\varepsilon(t, x)\partial_x u_\varepsilon(t, x) + \partial_x^3 u_\varepsilon(t, x) \\ + r(t, x)\partial_x u_\varepsilon(t, x) - \varepsilon\partial_x^2 u_\varepsilon + \varepsilon\partial_x^4 u_\varepsilon = f(t, x) & (t, x) \in R, \\ u_\varepsilon(0, x) = 0 & x \in (0, 1), \\ u_\varepsilon(t, 0) = u_\varepsilon(t, 1) = \partial_x^2 u_\varepsilon(t, 0) = \partial_x u_\varepsilon(t, 1) = 0 & t \in (0, T). \end{cases} \quad (4.14)$$

In the case  $r(t, x) = 0$  and  $p(t), q(t)$  are constants, the equation (4.14) becomes the KdV-Burgers-Kuramoto equation. For other choice of coefficients, (4.14) is a model for several problems that appear in different physical situations.

We establish the existence of a solution  $u_\varepsilon$  for (4.14), using the Faedo-Galerkin method. Then finding uniform estimates in  $\varepsilon$  we obtain Theorem 4.2 , as  $\varepsilon \rightarrow 0$ .

**Theorem 4.5.** *If  $f, \partial_t f$  are in  $L^2(R)$ , and  $p, q, r$  satisfy assumption (4.10), then (4.14) admits a solution such that*

$$\begin{aligned} u_\varepsilon &\in L^\infty(0, T, H^2(I)) \cap L^2(0, T, H^4(I)), \\ \partial_t u_\varepsilon &\in L^\infty(0, T, L^2(I)) \cap L^2(0, T, H^2(I)). \end{aligned}$$

*Proof.* To prove the existence of a solution to (4.14), we choose the basis  $(e_j)_{j \in \mathbb{N}^*}$  of  $H^4(I)$  (see Lemma 4.4), orthonormal in  $L^2(I)$ , defined as a subset of the eigenfunctions for the problem

$$\begin{cases} e_j^{(4)} = \lambda_j e_j, & j \in \mathbb{N}^*, \\ e_j(0) = e_j(1) = e_j''(0) = e_j'(1) = 0. \end{cases}$$

Then, we introduce the approximate solution  $u_{\varepsilon n}$  by

$$u_{\varepsilon n}(t) = \sum_{j=1}^n c_{nj}(t) e_j, \quad (4.15)$$

which satisfies the approximate problem

$$\left\{ \begin{array}{l} p(t) \int_0^1 \partial_t u_{\varepsilon n} e_j \, dx + q(t) \int_0^1 u_{\varepsilon n} \partial_x u_{\varepsilon n} e_j \, dx + \int_0^1 \partial_x^3 u_{\varepsilon n} e_j \, dx \\ + \int_0^1 r(t, x) \partial_x u_{\varepsilon n} e_j \, dx - \varepsilon \int_0^1 \partial_x^2 u_{\varepsilon n} e_j \, dx + \varepsilon \int_0^1 \partial_x^4 u_{\varepsilon n} e_j \, dx \\ = \int_0^1 f e_j \, dx, \\ u_{\varepsilon n}(0) = u_{0n}. \end{array} \right. \quad (4.16)$$

for all  $j = 1, \dots, n$  and  $0 \leq t \leq T$ .

Problem (4.16) is equivalent to a system of  $n$  uncoupled nonlinear ordinary differential equations. So, this solution exists in some interval  $(0, T')$  with  $T' \leq T$  (see for example [15]). The a priori estimate (4.17) that will be given, shows that  $T' = T$ .  $\square$

### 4.3.1 A priori estimates

**Lemma 4.6.** *There exists a positive constant  $K_1$  independent of  $n$  and  $\varepsilon$ , such that for all  $t \in [0, T]$*

$$\alpha \|u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 \, ds \leq K_1, \quad (4.17)$$

where  $\alpha$  is given in (4.10).

*Proof.* Multiplying (4.16) by  $c_j$ , taking the summation with respect to  $j$  from 1 to  $n$ , and using (4.15), we get

$$\begin{aligned} & \frac{p(t)}{2} \frac{d}{dt} \int_0^1 u_{\varepsilon n}^2 \, dx + \varepsilon \int_0^1 (\partial_x u_{\varepsilon n})^2 \, dx + \varepsilon \int_0^1 (\partial_x^2 u_{\varepsilon n})^2 \, dx \\ & + \frac{1}{2} (\partial_x u(t, 0))^2 - \frac{1}{2} \int_0^1 \partial_x r(t, x) u_{\varepsilon n}^2 \, dx = \int_0^1 f u_{\varepsilon n} \, dx. \end{aligned}$$



Indeed, because of the boundary conditions, the integration by parts gives

$$\begin{aligned} q(t) \int_0^1 u_{\varepsilon n}^2 \partial_x u_{\varepsilon n} \, dx &= \frac{q(t)}{3} \int_0^1 \partial_x (u_{\varepsilon n})^3 \, dx = 0, \\ \int_0^1 \partial_x^3 u_{\varepsilon n} u_{\varepsilon n} \, dx &= - \int_0^1 \partial_x^2 u_{\varepsilon n} \partial_x u_{\varepsilon n} \, dx = \frac{1}{2} (\partial_x u(t, 0))^2, \\ \int_0^1 r(t, x) \partial_x u_{\varepsilon n} u_{\varepsilon n} \, dx &= \int_0^1 r(t, x) \partial_x \left( \frac{u_{\varepsilon n}^2}{2} \right) \, dx = -\frac{1}{2} \int_0^1 \partial_x r(t, x) u_{\varepsilon n}^2 \, dx. \end{aligned}$$

Then

$$\frac{p(t)}{2} \frac{d}{dt} \int_0^1 u_{\varepsilon n}^2 \, dx + \varepsilon \int_0^1 (\partial_x^2 u_{\varepsilon n})^2 \, dx \leq \frac{1}{2} \int_0^1 \partial_x r(t, x) u_{\varepsilon n}^2 \, dx + \int_0^1 f u_{\varepsilon n} \, dx, \quad (4.18)$$

by integrating (4.18) with respect to  $t$  ( $t \in (0, T)$ ), and according to (4.10), using Cauchy-Schwarz inequality, we find that

$$\begin{aligned} &\frac{\alpha}{2} \|u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 \, ds \\ &\leq \int_0^t \|f(s)\|_{L^2(I)} \|u_{\varepsilon n}(s)\|_{L^2(I)} \, ds + \frac{\beta}{2} \int_0^t \|u_{\varepsilon n}(s)\|_{L^2(I)}^2 \, ds. \end{aligned}$$

By the elementary inequality

$$|ab| \leq \frac{\xi}{2} a^2 + \frac{b^2}{2\xi}, \quad \forall a, b \in \mathbb{R}, \quad \forall \xi > 0, \quad (4.19)$$

with  $\xi = 1$ , we obtain

$$\begin{aligned} &\frac{\alpha}{2} \|u_{\varepsilon n}\|_{L^2(I)}^2 + \frac{\varepsilon}{2} \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 \, ds \\ &\leq \frac{1}{2} \int_0^t \|f(s)\|_{L^2(I)}^2 \, ds + \frac{1}{2} \int_0^t \|u_{\varepsilon n}(s)\|_{L^2(I)}^2 \, ds + \frac{\beta}{2} \int_0^t \|u_{\varepsilon n}(s)\|_{L^2(I)}^2 \, ds. \end{aligned}$$

Hence

$$\begin{aligned} & \alpha \|u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \\ & \leq \int_0^t \|f(s)\|_{L^2(I)}^2 ds + (\beta + 1) \int_0^t \|u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds, \end{aligned}$$

and

$$\begin{aligned} & \alpha \|u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \\ & \leq (\beta + 1) \int_0^t \left( \|u_{\varepsilon n}(s)\|_{L^2(I)}^2 + \varepsilon \int_0^s \|\partial_x^2 u_{\varepsilon n}(\tau)\|_{L^2(I)}^2 d\tau \right) ds \\ & \quad + \int_0^t \|f(s)\|_{L^2(I)}^2 ds. \end{aligned}$$

As  $f$  is in  $L^2(R)$ , there exists a positive constant  $C_1$  independent of  $n$  such that

$$\begin{aligned} & \alpha \|u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \\ & \leq C_1 + (\beta + 1) \int_0^t \left( \|u_{\varepsilon n}(s)\|_{L^2(I)}^2 + \varepsilon \int_0^s \|\partial_x^2 u_{\varepsilon n}(\tau)\|_{L^2(I)}^2 d\tau \right) ds, \end{aligned}$$

then, by Gronwall's inequality, we deduce that

$$\alpha \|u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \leq C_1 \exp((\beta + 1)t).$$

Taking  $K_1 = C_1 \exp((\beta + 1)T)$ , we obtain

$$\alpha \|u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \leq K_1.$$

□

**Lemma 4.7.** *There exists a positive constant  $K_2(\varepsilon)$  independent of  $n$ , such that for all  $t \in [0, T]$*

$$\alpha \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^4 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \leq K_2(\varepsilon),$$

where  $\alpha$  is given in (4.10).

*Proof.* As  $\partial_x^4 e_j = \lambda_j e_j$ , we have

$$\sum_{j=1}^n c_j(t) \lambda_j e_j = \sum_{j=1}^n c_j(t) \partial_x^4 e_j = \partial_x^4 u_{\varepsilon n}(t).$$

Multiplying both sides of (4.16) by  $c_j \lambda_j$ , taking the summation with respect to  $j$  from 1 to  $n$  and using the previous relation, we obtain

$$\begin{aligned} & \frac{p(t)}{2} \frac{d}{dt} \int_0^1 (\partial_x^2 u_{\varepsilon n})^2 dx + \varepsilon \int_0^1 (\partial_x^4 u_{\varepsilon n})^2 dx \\ &= -q(t) \int_0^1 u_{\varepsilon n} \partial_x u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} dx - \int_0^1 \partial_x^3 u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} dx \\ & - \int_0^1 r(t, x) \partial_x u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} dx + \varepsilon \int_0^1 \partial_x^2 u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} dx + \int_0^1 f \partial_x^4 u_{\varepsilon n} dx. \end{aligned} \quad (4.20)$$

Using (4.10) and (4.19) with  $\xi = \frac{3}{\varepsilon}$ , we obtain

$$\left| \int_0^1 \partial_x^3 u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} dx \right| \leq \frac{3}{2\varepsilon} \|\partial_x^3 u_{\varepsilon n}\|_{L^2(I)}^2 + \frac{\varepsilon}{6} \|\partial_x^4 u_{\varepsilon n}\|_{L^2(I)}^2, \quad (4.21)$$

$$\left| \int_0^1 f \partial_x^4 u_{\varepsilon n} dx \right| \leq \frac{3}{2\varepsilon} \|f\|_{L^2(I)}^2 + \frac{\varepsilon}{6} \|\partial_x^4 u_{\varepsilon n}\|_{L^2(I)}^2, \quad (4.22)$$

$$\left| \int_0^1 r(t, x) \partial_x u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} dx \right| \leq \frac{3\beta^2}{2\varepsilon} \|\partial_x u_{\varepsilon n}\|_{L^2(I)}^2 + \frac{\varepsilon}{6} \|\partial_x^4 u_{\varepsilon n}\|_{L^2(I)}^2. \quad (4.23)$$

Now (4.19) with  $\xi = 3$ , gives

$$\varepsilon \int_0^1 \partial_x^2 u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} dx \leq \frac{3\varepsilon}{2} \int_0^1 (\partial_x^2 u_{\varepsilon n})^2 dx + \frac{\varepsilon}{6} \int_0^1 (\partial_x^4 u_{\varepsilon n})^2 dx. \quad (4.24)$$

By the Ehrling inequality, there exists a positive constant  $\eta(\varepsilon, \beta)$ , such that

$$\|\partial_x^3 u_{\varepsilon n}\|_{L^2(I)}^2 \leq \frac{\varepsilon^2}{9} \|\partial_x^4 u_{\varepsilon n}\|_{L^2(I)}^2 + \eta(\varepsilon) \|u_{\varepsilon n}\|_{L^2(I)}^2.$$

Using the previous inequality, (4.21) becomes

$$\left| \int_0^1 \partial_x^3 u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} \, dx \right| \leq \frac{\varepsilon}{3} \|\partial_x^4 u_{\varepsilon n}\|_{L^2(I)}^2 + C_2 \|u_{\varepsilon n}\|_{L^2(I)}^2. \quad (4.25)$$

where  $C_2 = \eta(\varepsilon) \frac{3}{2\varepsilon}$ .

Now, we have to estimate the first term of the right-hand side of (4.20). An integration by parts gives

$$\begin{aligned} \int_0^1 u_{\varepsilon n} \partial_x u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} \, dx &= - \int_0^1 \partial_x (u_{\varepsilon n} \partial_x u_{\varepsilon n}) \partial_x^3 u_{\varepsilon n} \, dx \\ &= - \int_0^1 (\partial_x u_{\varepsilon n})^2 \partial_x^3 u_{\varepsilon n} \, dx - \int_0^1 u_{\varepsilon n} \partial_x^2 u_{\varepsilon n} \partial_x^3 u_{\varepsilon n} \, dx \\ &= \int_0^1 \partial_x (\partial_x u_{\varepsilon n})^2 \partial_x^2 u_{\varepsilon n} \, dx - \frac{1}{2} \int_0^1 u_{\varepsilon n} \partial_x (\partial_x^2 u_{\varepsilon n})^2 \, dx \\ &= \frac{5}{2} \int_0^1 \partial_x u_{\varepsilon n} (\partial_x^2 u_{\varepsilon n})^2 \, dx. \end{aligned}$$

Then

$$\left| q(t) \int_0^1 u_{\varepsilon n} \partial_x u_{\varepsilon n} \partial_x^4 u_{\varepsilon n} \, dx \right| \leq \frac{5\beta}{2} \|\partial_x u_{\varepsilon n}\|_{L^\infty(I)} \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2. \quad (4.26)$$

By integrating (4.20) between 0 and  $t$ , the estimates (4.22), (4.23), (4.24), (4.25) and (4.26) imply

$$\begin{aligned} &\frac{\alpha}{2} \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \frac{\varepsilon}{6} \int_0^t \|\partial_x^4 u_{\varepsilon n}(s)\|_{L^2(I)}^2 \, ds \\ &\leq \frac{3}{2\varepsilon} \int_0^t \|f(s)\|_{L^2(I)}^2 \, ds + \frac{5\beta}{2} \int_0^t \|\partial_x u_{\varepsilon n}\|_{L^\infty(I)} \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 \, ds \\ &+ \frac{3\varepsilon}{2} \int_0^t \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 \, ds + C_2 \int_0^t \|u_{\varepsilon n}\|_{L^2(I)}^2 \, ds + \frac{3\beta^2}{2\varepsilon} \int_0^t \|\partial_x u_{\varepsilon n}\|_{L^2(I)}^2 \, ds. \end{aligned}$$

Using the injection of  $H_0^1(I)$  in  $L^\infty(I)$  and Poincaré's inequality, we obtain

$$\begin{aligned} & \frac{\alpha}{2} \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \frac{\varepsilon}{6} \int_0^t \|\partial_x^4 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \\ & \leq \int_0^t \|\partial_x^2 u_{\varepsilon n}(s)\|_{L^2(I)}^2 \left( \frac{5\beta}{2} \|u_{\varepsilon n}(s)\|_{H^2(I)}^2 + \frac{3\varepsilon}{2} + \frac{C_2}{4} + \frac{3\beta^2}{4\varepsilon} \right) ds \\ & \quad + \frac{3}{2\varepsilon} \int_0^t \|f(s)\|_{L^2(I)}^2 ds. \end{aligned}$$

Observe that  $f \in L^2(R)$ . Then, from (4.17), there exists a positive constant  $C_3(\varepsilon)$  such that

$$\begin{aligned} & \alpha \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^4 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \\ & \leq C_3(\varepsilon) + \int_0^t \left( \frac{5\beta}{2} \|u_{\varepsilon n}(s)\|_{H^2(I)}^2 + \frac{3\varepsilon}{2} + \frac{C_2}{4} + \frac{3\beta^2}{4\varepsilon} \right) \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 ds, \end{aligned}$$

so,

$$\begin{aligned} & \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^4 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \\ & \leq C_3(\varepsilon) + \int_0^t \left( \frac{5\beta}{2} \|u_{\varepsilon n}(s)\|_{H^2(I)}^2 + C_4(\varepsilon) \right) \\ & \quad \left( \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^s \|\partial_x^4 u_{\varepsilon n}(\tau)\|_{L^2(I)}^2 d\tau \right) ds. \end{aligned}$$

where  $C_4(\varepsilon) = \frac{3\varepsilon}{2} + \frac{C_2}{4} + \frac{3\beta^2}{4\varepsilon}$ . Gronwall's inequality shows that

$$\begin{aligned} & \alpha \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^4 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \\ & \leq C_3(\varepsilon) \exp \left( \int_0^t \left( \frac{5\beta}{2} \|u_{\varepsilon n}(s)\|_{H^2(I)}^2 + C_4(\varepsilon) \right) ds \right). \end{aligned}$$

From (4.17), there exists a positive constant  $K_2(\varepsilon)$  independent of  $n$ , such that

$$\alpha \|\partial_x^2 u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^4 u_{\varepsilon n}(s)\|_{L^2(I)}^2 ds \leq K_2(\varepsilon).$$

□

**Lemma 4.8.** *There exists a positive constant  $K_3(\varepsilon)$  independent of  $n$ , such that for all  $t \in [0, T]$*

$$\alpha \|\partial_t u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|(\partial_t(\partial_x^2 u_{\varepsilon n}(s)))\|_{L^2(I)}^2 ds \leq K_3(\varepsilon).$$

*Proof.* Differentiating (4.16) with respect to  $t$ , and replacing  $e_j$  by  $\partial_t u_{\varepsilon n}$ , we get

$$\begin{aligned} & \int_0^1 \partial_t(p(t)\partial_t u_{\varepsilon n}) \partial_t u_{\varepsilon n} dx + \int_0^1 \partial_t(q(t)u_{\varepsilon n}\partial_x u_{\varepsilon n}) \partial_t u_{\varepsilon n} dx \\ & + \int_0^1 \partial_t(\partial_x^3 u_{\varepsilon n}) \partial_t u_{\varepsilon n} dx + \int_0^1 \partial_t(r(t,x)\partial_x u_{\varepsilon n}) \partial_t u_{\varepsilon n} dx \\ & - \varepsilon \int_0^1 \partial_t(\partial_x^2 u_{\varepsilon n}) \partial_t u_{\varepsilon n} dx + \varepsilon \int_0^1 \partial_t(\partial_x^4 u_{\varepsilon n}) \partial_t u_{\varepsilon n} dx \\ & = \int_0^1 \partial_t f \partial_t u_{\varepsilon n} dx. \end{aligned}$$

By the boundary conditions of (4.14), and (4.10) we obtain

$$\begin{aligned} & \alpha \|\partial_t u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|(\partial_t(\partial_x^2 u_{\varepsilon n}(s)))\|_{L^2(I)}^2 ds \\ & \leq \frac{1}{2} \|\partial_t f\|_{L^2(R)}^2 + \frac{\beta}{2} \|u_{\varepsilon n}\|_{L^\infty(I)} \|\partial_x u_{\varepsilon n}\|_{L^2(R)}^2 + \beta \|\partial_x u_{\varepsilon n}\|_{L^2(R)}^2 \\ & + \left( \frac{1}{2} + \frac{3\beta}{2} \|u_{\varepsilon n}\|_{L^\infty(R)}^2 + 3\beta \|\partial_x u_{\varepsilon n}\|_{L^\infty(R)}^2 \right) \|\partial_t u_{\varepsilon n}\|_{L^2(R)}^2. \end{aligned}$$

Then, Gronwall's inequality shows that

$$\alpha \|\partial_t u_{\varepsilon n}\|_{L^2(I)}^2 + \varepsilon \int_0^t \|(\partial_t(\partial_x^2 u_{\varepsilon n}(s)))\|_{L^2(I)}^2 ds \leq K_3(\varepsilon).$$

□

### 4.3.2 Existence of solution for the approximated problem

Lemmas 4.6, 4.7 and 4.8 show that the Galerkin approximation  $u_{\varepsilon n}$  is bounded in  $L^\infty(0, T, H^2(I))$ , and  $\varepsilon \partial_x^4 u_{\varepsilon n}$ ,  $\partial_t u_{\varepsilon n}$  are bounded in  $L^2(R)$ .

So, it is possible to extract a subsequence from  $u_{\varepsilon n}$ , still denoted  $u_{\varepsilon n}$ , such that

$$u_{\varepsilon n} \rightarrow u_\varepsilon \quad \text{weakly in } L^2(0, T, H_0^1(I)), \quad (4.27)$$

$$u_{\varepsilon n} \rightarrow u_\varepsilon \quad \text{strongly in } L^2(0, T, L^2(I)), \quad (4.28)$$

$$\varepsilon \partial_x^4 u_{\varepsilon n} \rightarrow \varepsilon \partial_x^4 u_\varepsilon \quad \text{weakly in } L^2(0, T, L^2(I)), \quad (4.29)$$

$$\partial_t u_{\varepsilon n} \rightarrow \partial_t u_\varepsilon, \quad \text{weakly in } L^2(0, T, L^2(I)). \quad (4.30)$$

Note that (4.30) implies

$$\int_0^T \int_0^1 p(t) \partial_t u_{\varepsilon n} w \, dx \, dt \longrightarrow \int_0^T \int_0^1 p(t) \partial_t u_\varepsilon w \, dx \, dt, \quad \forall w \in L^2(R).$$

From (4.27) and (4.28)

$$u_{\varepsilon n} \partial_x u_{\varepsilon n} \longrightarrow u_\varepsilon \partial_x u_\varepsilon \quad \text{weakly in } L^2(R),$$

then

$$\int_0^T \int_0^1 q(t) u_{\varepsilon n} \partial_x u_{\varepsilon n} w \, dx \, dt \longrightarrow \int_0^T \int_0^1 q(t) u_\varepsilon \partial_x u_\varepsilon w \, dx \, dt, \quad \forall w \in L^2(R).$$

$$\int_0^T \int_0^1 \partial_x^3 u_{\varepsilon n} w \, dx \, dt \longrightarrow \int_0^T \int_0^1 \partial_x^3 u_\varepsilon w \, dx \, dt, \quad \forall w \in L^2(R),$$

$$\int_0^T \int_0^1 r(t, x) \partial_x u_{\varepsilon n} w \, dx \, dt \longrightarrow \int_0^T \int_0^1 r(t, x) \partial_x u_\varepsilon w \, dx \, dt, \quad \forall w \in L^2(R),$$

and

$$\varepsilon \int_0^T \int_0^1 (-\partial_x^2 u_{\varepsilon n} + \partial_x^4 u_{\varepsilon n}) w \, dx \, dt \longrightarrow \varepsilon \int_0^T \int_0^1 (-\partial_x^2 u_\varepsilon + \partial_x^4 u_\varepsilon) w \, dx \, dt, \quad \forall w \in L^2(R).$$

Using these properties, we can pass to the limit in (4.16) as  $n \rightarrow +\infty$ . Consequently, there exists a solution  $u_\varepsilon$  of (4.14).

## 4.4 Passage to the limit in $\varepsilon$

Our goal in this section is to find uniform estimates in  $\varepsilon$ , to pass to the limit in (4.14) when  $\varepsilon \rightarrow 0$ .

**Lemma 4.9.** *Under the hypotheses of Theorem 4.2, for all  $\varepsilon \in (0, \alpha)$ , the solution of (4.14) satisfies the estimate*

$$\|u_\varepsilon\|_{L^2(I)}^2 + (\alpha - \varepsilon) \int_0^t \|\partial_x u_\varepsilon(s)\|_{L^2(I)}^2 ds + \varepsilon \int_0^t \|\partial_x^2 u_\varepsilon(s)\|_{L^2(I)}^2 ds \leq K_4,$$

where  $\alpha$  is given in (4.10) and  $K_4$  is a positive constant independent of  $\varepsilon$ .

*Proof.* Multiplying both sides of (4.14) by  $u_\varepsilon$  and integrating between 0 and 1, we obtain

$$\begin{aligned} & \frac{p(t)}{2} \frac{d}{dt} \int_0^1 u_\varepsilon^2 dx + \varepsilon \int_0^1 (\partial_x u_\varepsilon)^2 dx + \varepsilon \int_0^1 (\partial_x^2 u_\varepsilon)^2 dx \\ & \frac{1}{2} (\partial_x u(t, 0))^2 - \frac{1}{2} \int_0^1 \partial_x r(t, x) u_\varepsilon^2 dx = \int_0^1 f u_\varepsilon dx. \end{aligned}$$

Following the same steps as in lemma 4.6, we prove that there exists a constant  $K_1$  independent of  $\varepsilon$ , such that

$$\alpha \|u_\varepsilon\|_{L^2(I)}^2 + \varepsilon \int_0^t \|\partial_x^2 u_\varepsilon(s)\|_{L^2(I)}^2 ds \leq K_1. \quad (4.31)$$

Now, we multiply both sides of (4.14) by  $e^x u_\varepsilon$  and integrate between 0 and 1, to get

$$\begin{aligned} & p(t) \int_0^1 e^x u_\varepsilon \partial_t u_\varepsilon dx + \int_0^1 e^x u_\varepsilon \partial_x^3 u_\varepsilon dx \\ & - \varepsilon \int_0^1 e^x u_\varepsilon \partial_x^2 u_\varepsilon dx + \varepsilon \int_0^1 e^x u_\varepsilon \partial_x^4 u_\varepsilon dx \\ & = -q(t) \int_0^1 e^x u_\varepsilon^2 \partial_x u_\varepsilon dx - \int_0^1 r(t, x) e^x u_\varepsilon \partial_x u_\varepsilon dx + \int_0^1 f e^x u_\varepsilon dx. \end{aligned} \quad (4.32)$$



Taking into account the boundary conditions of Problem (4.14), an integration by parts gives

$$\int_0^1 e^x u_\varepsilon \partial_t u_\varepsilon \, dx = \frac{1}{2} \frac{d}{dt} \int_0^1 e^x u_\varepsilon^2 \, dx,$$

$$\begin{aligned} \int_0^1 e^x u \partial_x^3 u_\varepsilon \, dx &= - \int_0^1 e^x u_\varepsilon \partial_x^2 u_\varepsilon \, dx - \int_0^1 e^x \partial_x u \partial_x^2 u_\varepsilon \, dx \\ &= \int_0^1 e^x u_\varepsilon \partial_x u_\varepsilon \, dx + \int_0^1 e^x (\partial_x u_\varepsilon)^2 \, dx - \frac{1}{2} \int_0^1 e^x \partial_x (\partial_x u_\varepsilon)^2 \, dx \\ &= -\frac{1}{2} \int_0^1 e^x u_\varepsilon^2 \, dx + \frac{3}{2} \int_0^1 e^x (\partial_x u_\varepsilon)^2 \, dx + \frac{1}{2} (\partial_x u(t, 0))^2, \end{aligned}$$

$$\begin{aligned} \int_0^1 e^x u_\varepsilon \partial_x^2 u_\varepsilon \, dx &= - \int_0^1 e^x u_\varepsilon \partial_x u_\varepsilon \, dx - \int_0^1 e^x (\partial_x u_\varepsilon)^2 \, dx \\ &= \frac{1}{2} \int_0^1 e^x u_\varepsilon^2 \, dx - \int_0^1 e^x (\partial_x u_\varepsilon)^2 \, dx, \end{aligned}$$

$$\begin{aligned} \int_0^1 e^x u_\varepsilon \partial_x^4 u_\varepsilon \, dx &= - \int_0^1 e^x u_\varepsilon \partial_x^3 u_\varepsilon \, dx - \int_0^1 e^x \partial_x u_\varepsilon \partial_x^3 u_\varepsilon \, dx \\ &= \int_0^1 e^x u_\varepsilon \partial_x^2 u_\varepsilon \, dx + \int_0^1 e^x \partial_x u_\varepsilon \partial_x^2 u_\varepsilon \, dx + \int_0^1 e^x \partial_x u_\varepsilon \partial_x^2 u_\varepsilon \, dx + \int_0^1 e^x (\partial_x^2 u_\varepsilon)^2 \, dx \\ &= - \int_0^1 e^x u_\varepsilon \partial_x u_\varepsilon \, dx - \int_0^1 e^x (\partial_x u_\varepsilon)^2 \, dx + \int_0^1 e^x \partial_x (\partial_x u_\varepsilon)^2 \, dx + \int_0^1 e^x (\partial_x^2 u_\varepsilon)^2 \, dx \\ &= \frac{1}{2} \int_0^1 e^x u_\varepsilon^2 \, dx - 2 \int_0^1 e^x (\partial_x u_\varepsilon)^2 \, dx + \int_0^1 e^x (\partial_x^2 u_\varepsilon)^2 \, dx - (\partial_x u_\varepsilon(t, 0))^2, \end{aligned}$$

$$\begin{aligned} \int_0^1 r(t, x) e^x u_\varepsilon \partial_x u_\varepsilon \, dx &= \frac{1}{2} \int_0^1 r(t, x) e^x \partial_x (u_\varepsilon)^2 \, dx \\ &= -\frac{1}{2} \int_0^1 \partial_x r(t, x) e^x u_\varepsilon^2 \, dx - \frac{1}{2} \int_0^1 r(t, x) e^x u_\varepsilon^2 \, dx, \end{aligned}$$

and

$$\int_0^1 e^x u_\varepsilon^2 \partial_x u_\varepsilon \, dx = -\frac{1}{3} \int_0^1 e^x u_\varepsilon^3 \, dx.$$

Using the previous calculations, (4.33) becomes

$$\begin{aligned} &\frac{p(t)}{2} \frac{d}{dt} \int_0^1 e^x u_\varepsilon^2 \, dx + \left( \frac{3}{2} - \varepsilon \right) \int_0^1 e^x (\partial_x u_\varepsilon)^2 \, dx \\ &+ \left( \frac{1}{2} - \varepsilon \right) (\partial_x u(t, 0))^2 + \varepsilon \int_0^1 e^x (\partial_x^2 u_\varepsilon)^2 \, dx \\ &= \int_0^1 \frac{e^x}{2} (\partial_x r(t, x) + r(t, x)) u_\varepsilon^2 \, dx + \frac{q(t)}{3} \int_0^1 e^x u_\varepsilon^3 \, dx + \int_0^1 f e^x u_\varepsilon \, dx. \end{aligned}$$

As  $1 \leq e^x \leq e$  for all  $x \in [0, 1]$ , by integrating from 0 at  $t$  ( $t \in (0, T)$ ) and using (4.10), we find thanks to Cauchy-Schwarz inequality

$$\begin{aligned} &\alpha \|u_\varepsilon\|_{L^2(I)}^2 + (3\alpha - 2\varepsilon) \int_0^t \|\partial_x u_\varepsilon(s)\|_{L^2(I)}^2 \, ds + \varepsilon \int_0^t \|\partial_x^2 u_\varepsilon(s)\|_{L^2(I)}^2 \, ds \\ &\leq e(3\beta + 2\varepsilon + 1) \int_0^t \|u_\varepsilon(s)\|_{L^2(I)}^2 \, ds + e \int_0^t \|f(s)\|_{L^2(I)}^2 \, ds + \frac{2e\beta}{3} \int_0^t \|u_\varepsilon\|_{L^3(I)}^3 \, ds. \end{aligned}$$

Now, we will get an estimate for the last term in the previous inequality. Since

$$\|u_\varepsilon\|_{L^\infty(I)}^2 \leq 2\|u_\varepsilon\|_{L^2(I)} \|\partial_x u_\varepsilon\|_{L^2(I)},$$

then

$$\begin{aligned} \frac{2e\beta}{3} \|u_\varepsilon\|_{L^3(I)}^3 &\leq \frac{2e\beta}{3} \|u_\varepsilon\|_{L^\infty(I)} \|u_\varepsilon\|_{L^2(I)}^2 \\ &\leq e\beta \|\partial_x u_\varepsilon\|_{L^2(I)}^{\frac{1}{2}} \|u_\varepsilon\|_{L^2(I)}^{\frac{5}{2}}. \end{aligned}$$

By Young's inequality  $|AB| \leq \frac{|A|^p}{p} + \frac{|B|^{p'}}{p'}$  with  $1 < p < \infty$  and  $p' = \frac{p}{p-1}$ , choosing  $p = 4$  (then  $p' = \frac{4}{3}$ )

$$A = \sqrt{2}\alpha^{\frac{1}{4}} \|\partial_x u_\varepsilon\|_{L^2(I)}^{\frac{1}{2}},$$

$$B = \frac{e\beta}{\sqrt{2}\alpha^{\frac{1}{4}}} \|u_\varepsilon\|_{L^2(I)}^{\frac{5}{2}},$$

we obtain

$$e\beta \|\partial_x u_\varepsilon\|_{L^2(I)}^{\frac{1}{2}} \|u_\varepsilon\|_{L^2(I)}^{\frac{5}{2}} \leq \alpha \|\partial_x u_\varepsilon\|_{L^2(I)}^2 + \frac{3}{4} \left( \frac{e\beta}{\sqrt{2}\alpha^{\frac{1}{4}}} \right)^{\frac{4}{3}} \|u_\varepsilon\|_{L^2(I)}^{\frac{10}{3}}.$$

On the other hand,  $f \in L^2(R)$ , then there exists a constant  $C_5$  independent of  $\varepsilon$  such that

$$\begin{aligned} & \alpha \|u_\varepsilon\|_{L^2(I)}^2 + 2(\alpha - \varepsilon) \int_0^t \|\partial_x u_\varepsilon(s)\|_{L^2(I)}^2 ds + \varepsilon \int_0^t \|\partial_x^2 u_\varepsilon(s)\|_{L^2(I)}^2 ds \\ & \leq C_5 + e(3\beta + 2\varepsilon + 1) \int_0^t \|u_\varepsilon(s)\|_{L^2(I)}^2 ds \\ & \quad + \frac{3}{4} \left( \frac{e\beta}{\sqrt{2}\alpha^{\frac{1}{4}}} \right)^{\frac{4}{3}} \int_0^t \|u_\varepsilon\|_{L^2(I)}^{\frac{4}{3}} \|u_\varepsilon\|_{L^2(I)}^2 ds. \end{aligned}$$

As  $\varepsilon$  goes to 0 we can choose  $\varepsilon \in (0, \alpha)$ . Then, we deduce that

$$\varphi(t) = \alpha \|u_\varepsilon\|_{L^2(I)}^2 + (\alpha - \varepsilon) \int_0^t \|\partial_x u_\varepsilon(s)\|_{L^2(I)}^2 ds + \varepsilon \int_0^t \|\partial_x^2 u_\varepsilon(s)\|_{L^2(I)}^2 ds$$

verifies the following inequality

$$\varphi(t) \leq C_5 + \int_0^t \left( C_6 \|u_\varepsilon\|_{L^2(I)}^{\frac{4}{3}} + C_7 \right) \varphi(s) ds,$$

where  $C_6 = \frac{3}{4} \left( \frac{e\beta}{\sqrt{2}\alpha^{\frac{1}{4}}} \right)^{\frac{4}{3}}$  and  $C_7 = e(3\beta + 2\varepsilon + 1)$ .

By the Gronwall's inequality, we obtain

$$\varphi(t) \leq C_5 \exp \left( \int_0^t C_6 \|\partial_x u_\varepsilon\|_{L^2(I)}^{\frac{4}{3}} ds + C_7 T \right).$$

From (4.31) we have a bound for  $\int_0^t \|u_\varepsilon\|_{L^2(I)}^{4/3} ds$ , then there exists a positive constant  $K_4$  independent of  $\varepsilon$  such that

$$\|u_\varepsilon\|_{L^2(I)}^2 + (\alpha - \varepsilon) \int_0^t \|\partial_x u_\varepsilon(s)\|_{L^2(I)}^2 ds + \varepsilon \int_0^t \|\partial_x^2 u_\varepsilon(s)\|_{L^2(I)}^2 ds \leq K_4$$

□

**Lemma 4.10.** *Under the hypotheses of Theorem 4.2, for all  $\varepsilon > 0$ , the solution of (4.14) satisfies the estimate*

$$\alpha \|\partial_t u_\varepsilon\|_{L^2(I)}^2 + C \int_0^t \|\partial_t(\partial_x u_\varepsilon(s))\|_{L^2(I)}^2 ds + \varepsilon \int_0^t \|\partial_t(\partial_x^2 u_\varepsilon(s))\|_{L^2(I)}^2 ds \leq K_5$$

where  $C$  and  $K_5$  are a positive constants independent of  $\varepsilon$ .

*Proof.* Differentiating (4.14) with respect to  $t$ , multiplying both sides by  $e^x \partial_t u_\varepsilon$  and integrating between 0 and 1, we obtain

$$\begin{aligned} & p(t) \int_0^1 e^x \partial_t u_\varepsilon \partial_t^2 u_\varepsilon dx + p'(t) \int_0^1 e^x (\partial_t u_\varepsilon)^2 dx + \int_0^1 e^x \partial_t (q(t) u_\varepsilon \partial_x u_\varepsilon) \partial_t u_\varepsilon dx \\ & + \int_0^1 e^x \partial_t (\partial_x^3 u_\varepsilon) \partial_t u_\varepsilon dx + \int_0^1 e^x \partial_t (r(t, x) \partial_x u_\varepsilon) \partial_t u_\varepsilon dx \\ & - \varepsilon \int_0^1 e^x \partial_t (\partial_x^2 u_\varepsilon) \partial_t u_\varepsilon dx + \varepsilon \int_0^1 e^x \partial_t (\partial_x^4 u_\varepsilon) \partial_t u_\varepsilon dx \\ & = \int_0^1 e^x \partial_t f \partial_t u_\varepsilon dx. \end{aligned} \tag{4.33}$$

By the boundary conditions of (4.14), an integration by parts gives

$$\int_0^1 e^x \partial_t u_\varepsilon \partial_t^2 u_\varepsilon dx = \frac{1}{2} \frac{d}{dt} \int_0^1 e^x (\partial_t u_\varepsilon)^2 dx,$$

$$\begin{aligned} \int_0^1 e^x \partial_t (\partial_x^2 u_\varepsilon) \partial_t u_\varepsilon dx &= \frac{1}{2} \int_0^1 e^x (\partial_t u_\varepsilon)^2 dx - \int_0^1 e^x (\partial_t (\partial_x u_\varepsilon))^2 dx, \\ \int_0^1 e^x \partial_t (\partial_x^4 u_\varepsilon) \partial_t u_\varepsilon dx &= \frac{1}{2} \int_0^1 e^x (\partial_t u_\varepsilon)^2 dx - 2 \int_0^1 e^x (\partial_t (\partial_x u_\varepsilon))^2 dx \\ &\quad + \int_0^1 e^x (\partial_t (\partial_x^2 u_\varepsilon))^2 dx - (\partial_t (\partial_x u_\varepsilon(t, 0)))^2, \end{aligned}$$

$$\begin{aligned} \int_0^1 e^x \partial_t (r(t, x) \partial_x u_\varepsilon) \partial_t u_\varepsilon dx &= \int_0^1 e^x \partial_t r(t, x) \partial_x u_\varepsilon \partial_t u_\varepsilon dx - \frac{1}{2} \int_0^1 \partial_x r(t, x) e^x (\partial_t u_\varepsilon)^2 dx \\ &\quad - \frac{1}{2} \int_0^1 r(t, x) e^x (\partial_t u_\varepsilon)^2 dx, \end{aligned}$$

and

$$\begin{aligned} \int_0^1 e^x \partial_t (\partial_x^3 u_\varepsilon) \partial_t u_\varepsilon dx &= -\frac{1}{2} \int_0^1 e^x (\partial_t u_\varepsilon)^2 dx + \frac{3}{2} \int_0^1 e^x (\partial_t (\partial_x u_\varepsilon))^2 dx \\ &\quad + \frac{1}{2} (\partial_t (\partial_x u_\varepsilon(t, 0)))^2. \end{aligned}$$

Using the previous calculations, (4.33) becomes

$$\begin{aligned} &\frac{p(t)}{2} \frac{d}{dt} \int_0^1 e^x (\partial_t u_\varepsilon)^2 dx + \left( \frac{3}{2} - \varepsilon \right) \int_0^1 e^x (\partial_t (\partial_x u_\varepsilon))^2 dx \\ &+ \left( \frac{1}{2} - \varepsilon \right) (\partial_t (\partial_x u(t, 0)))^2 + \varepsilon \int_0^1 e^x (\partial_t (\partial_x^2 u_\varepsilon))^2 dx \\ &= \int_0^1 \frac{e^x}{2} (\partial_x r(t, x) + r(t, x) - p'(t) + 1) (\partial_t u_\varepsilon)^2 dx + \int_0^1 e^x \partial_t u_\varepsilon \partial_t f dx \\ &+ q'(t) \int_0^1 e^x u_\varepsilon \partial_x u_\varepsilon \partial_t u_\varepsilon dx + \int_0^1 e^x \partial_t r(t, x) \partial_x u_\varepsilon \partial_t u_\varepsilon dx \\ &+ q(t) \left( \int_0^1 e^x \partial_x u_\varepsilon (\partial_t u_\varepsilon)^2 dx + \int_0^1 e^x u_\varepsilon \partial_t u_\varepsilon \partial_t (\partial_x u_\varepsilon) dx \right). \end{aligned}$$

Moreover, we have

$$\begin{aligned} \left| \int_0^1 e^x \partial_t r(t, x) \partial_x u_\varepsilon \partial_t u_\varepsilon \, dx \right| &\leq \frac{\beta e}{2} \|\partial_x u_\varepsilon\|_{L^2(I)}^2 + \frac{\beta e}{2} \|\partial_t u_\varepsilon\|_{L^2(I)}^2 \\ \left| q'(t) \int_0^1 e^x u_\varepsilon \partial_x u_\varepsilon \partial_t u_\varepsilon \, dx \right| &\leq \frac{\beta e}{2} \|u_\varepsilon\|_{L^\infty(I)} \left( \|u_\varepsilon\|_{L^2(I)}^2 + \|\partial_t u_\varepsilon\|_{L^2(I)}^2 \right), \\ \left| q(t) \int_0^1 e^x u_\varepsilon (\partial_t u_\varepsilon)^2 \, dx \right| &\leq \beta e \|\partial_x u_\varepsilon\|_{L^2(I)} \|\partial_t u_\varepsilon\|_{L^2(I)}^2 \\ \left| q(t) \int_0^1 e^x u_\varepsilon \partial_t u_\varepsilon \partial_t (\partial_x u_\varepsilon) \, dx \right| &\leq \frac{\beta e}{2} \|u_\varepsilon\|_{L^\infty(I)} \left( \|\partial_t u_\varepsilon\|_{L^2(I)}^2 + \|\partial_t (\partial_x u_\varepsilon)\|_{L^2(I)}^2 \right) \end{aligned}$$

Then, by the Gronwall's inequality we prove that there exist two positive constants  $K_5$  and  $C$  independent of  $\varepsilon$ , such that

$$\alpha \|\partial_t u_\varepsilon\|_{L^2(I)}^2 + C \int_0^t \|\partial_t (\partial_x u_\varepsilon(s))\|_{L^2(I)}^2 \, ds + \varepsilon \int_0^t \|\partial_t (\partial_x^2 u_\varepsilon(s))\|_{L^2(I)}^2 \, ds \leq K_5$$

□

**Lemma 4.11.** *Under the hypotheses of Theorem 4.2 , (4.8) admits a solution  $u$ .*

*Proof.* By lemmas 4.9 and 4.10 it is possible to extract a subsequence from  $u_\varepsilon$ , still denoted  $u_\varepsilon$ , such that

$$u_\varepsilon \rightharpoonup u, \quad \text{weakly in } L^2(0, T, H_0^1(I)), \quad (4.34)$$

$$u_\varepsilon \partial_x u_\varepsilon \rightharpoonup u \partial_x u, \quad \text{weakly in } L^2(0, T, L^2(I)), \quad (4.35)$$

$$\varepsilon \partial_x^2 u_\varepsilon \rightarrow 0, \quad \text{weakly in } L^2(0, T, L^2(I)). \quad (4.36)$$

$$\partial_t u_\varepsilon \rightharpoonup \partial_t u, \quad \text{weakly in } L^2(0, T, L^2(I)). \quad (4.37)$$

From (4.15), for all  $w \in L^2(0, T, H^2(I) \cap H_0^1(I))$  with  $\partial_x w(t, 0) = 0$ , we have

$$\begin{aligned} & p(t) \int_0^T \int_0^1 \partial_t u_\varepsilon w \, dx \, dt + q(t) \int_0^T \int_0^1 u_\varepsilon \partial_x u_\varepsilon w \, dx \, dt + \int_0^T \int_0^1 \partial_x u_\varepsilon \partial_x^2 w \, dx \, dt \\ & + \int_0^T \int_0^1 r(t, x) \partial_x u_\varepsilon w \, dx \, dt - \varepsilon \int_0^T \int_0^1 \partial_x^2 u_\varepsilon w \, dx \, dt + \varepsilon \int_0^T \int_0^1 \partial_x^2 u_\varepsilon \partial_x^2 w \, dx \, dt \\ & = \int_0^T \int_0^1 f w \, dx \, dt. \end{aligned}$$

By (4.34)-(4.37), we can pass to the limit as  $\varepsilon \rightarrow 0$  and obtain

$$\begin{aligned} & p(t) \int_0^T \int_0^1 \partial_t u w \, dx \, dt + q(t) \int_0^T \int_0^1 u \partial_x u w \, dx \, dt + \int_0^T \int_0^1 \partial_x u \partial_x^2 w \, dx \, dt \\ & + \int_0^T \int_0^1 r(t, x) \partial_x u w \, dx \, dt = \int_0^T \int_0^1 f w \, dx \, dt. \end{aligned}$$

This completes the proof of existence part for Theorem 4.2 .  $\square$

**Lemma 4.12.** *Under the hypotheses of Theorem 4.2 , the solution of Problem (4.8) is unique.*

*Proof.* Let  $u_1, u_2$  be two solutions of (4.8) and  $u = u_1 - u_2$ . The equations satisfied by  $u_1$  and  $u_2$  lead to

$$\begin{aligned} & p(t) \partial_t u(t, x) + q(t) u(t, x) \partial_x u_1(t, x) + q(t) u_2(t, x) \partial_x u(t, x) \\ & + \partial_x^3 u(t, x) + r(t, x) \partial_x u(t, x) = 0. \end{aligned} \tag{4.38}$$

Multiplying both sides of (4.38) by  $e^x u$  and integrating from 0 to 1 (with respect to  $x$ ), we obtain

$$\begin{aligned} & p(t) \int_0^1 e^x u \partial_t u \, dx + q(t) \int_0^1 e^x u^2 \partial_x u_1 \, dx + q(t) \int_0^1 e^x u_2 u \partial_x u \, dx \\ & + \int_0^1 e^x \partial_x^3 u u \, dx + \int_0^1 e^x r(t, x) \partial_x u u \, dx = 0. \end{aligned}$$

Taking into account the boundary conditions of Problem (4.8), an integration by parts gives because

$$\begin{aligned} q(t) \int_0^1 e^x u^2 \partial_x u_1 \, dx &= -q(t) \int_0^1 e^x u^2 u_1 \, dx - 2q(t) \int_0^1 e^x u \partial_x u u_1 \, dx \\ \int_0^1 e^x u \partial_x^3 u \, dx &= 2 \int_0^1 e^x (\partial_x u)^2 \, dx + \frac{1}{2} (\partial_x u(t, 0))^2 \\ \int_0^1 r(t, x) e^x u \partial_x u \, dx &= -\frac{1}{2} \int_0^1 \partial_x r(t, x) e^x u^2 \, dx - \frac{1}{2} \int_0^1 r(t, x) e^x u^2 \, dx \end{aligned}$$

So,

$$\begin{aligned} &\frac{p(t)}{2} \frac{d}{dt} \|e^x u\|_{L^2(I)}^2 + 2\alpha \|\partial_x u\|_{L^2(I)}^2 + \frac{1}{2} (\partial_x u(t, 0))^2 \\ &= q(t) \int_0^1 e^x u^2 u_1 \, dx + 2q(t) \int_0^1 e^x u_1 u \partial_x u \, dx - q(t) \int_0^1 e^x u_2 u \partial_x u \, dx \\ &\quad - \frac{1}{2} \int_0^1 \partial_x r(t, x) e^x u^2 \, dx - \frac{1}{2} \int_0^1 r(t, x) e^x u^2 \, dx. \end{aligned}$$

By (4.19) with  $\xi = 2\alpha$ , we obtain

$$\begin{aligned} &\left| \int_0^1 q(t) (2u_1 - u_2) e^x u \partial_x u \, dx \right| \\ &\leq e\beta \left[ (2\|u_1\|_{L^\infty(R)} + \|u_2\|_{L^\infty(R)}) \|u\|_{L^2(I)} \right] \|\partial_x u\|_{L^2(I)} \\ &\leq \frac{e^2 \beta^2}{4\alpha} (2\|u_1\|_{L^\infty(R)} + \|u_2\|_{L^\infty(R)})^2 \|u\|_{L^2(I)}^2 + \alpha \|\partial_x u\|_{L^2(I)}^2, \end{aligned}$$

and

$$\left| -\frac{1}{2} \int_0^1 \partial_x r(t, x) e^x u^2 \, dx - \frac{1}{2} \int_0^1 r(t, x) e^x u^2 \, dx \right| \leq \beta e \|u\|_{L^2(I)}^2.$$

Finally, we deduce that there exists a positive constant  $K$ , such that

$$\frac{d}{dt} \|u\|_{L^2(I)}^2 \leq K \|u\|_{L^2(I)}.$$

Gronwall's lemma leads to  $u = 0$ . This completes the proof of Theorem 4.2 .  $\square$